

cpc

直得科技股份有限公司
CHIEFTEK PRECISION CO., LTD.



Will -SERIES

AC Linear Motor Servo Driver

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cpc CHIEFTEK PRECISION Co., LTD.

HEADQUARTERS
CHIEFTEK PRECISION Co., LTD.
No.3, Dali 1st Rd., Xinshi Dist., Southern Taiwan
Science Park, Tainan City, 741-45, Taiwan (R.O.C)
TEL:+886-6-505 5858 Http://www.chietek.com
E-mail:service@mail.chietek.com

CHIEFTEK PRECISION USA
2280 E. Locust Court,
Ontario, CA 91761, USA
Tel:+1-909-773-1200
Fax:+1-909-773-1202

cpc Europa GmbH
Industriepark 314,
D-78244 Göttingen, Germany
TEL:+49-7731-59130-38
FAX:+49-7731-59130-28

CHIEFTEK MACHINERY KUNSHAN Co., LTD.
No.1188, Hongqiao Rd, Kunshan,
Jiangsu, P.R. China
TEL:+86-512-5525 2831
FAX:+86-512-5525 2851



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Will-01-S51-EN



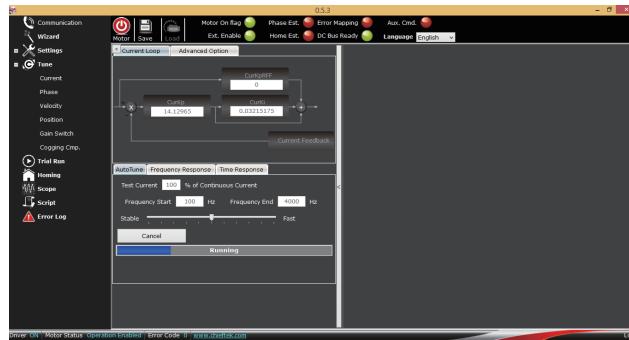
- Auto Tuning
- Auto Phasing
- Filter
- Response Bode plot
- Time response plot

Wizard

Step by step setup interface



Auto tune



- Auto tuning
- Visualized control loop
- User-friendly interface
- Highly efficient tuning algorithm
- Short tuning time
- Can tune for stable or fast system response

Auto tune(position)



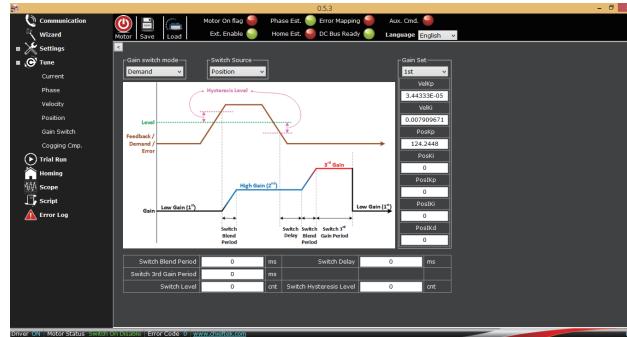
- Fast control loop up to 5k Hz
- Can test 3 groups of gain set
- Feedforward signal path
- Easy to fine tune
- Input response with profile position

Auto phasing



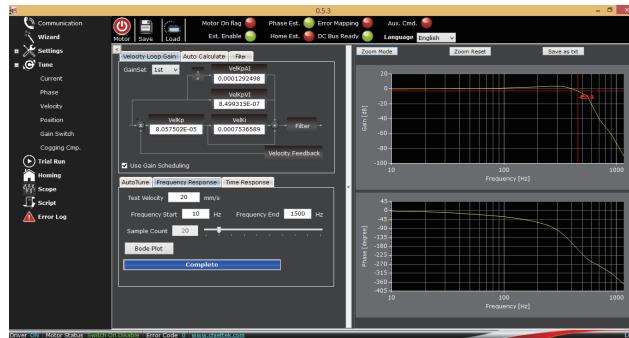
- Auto phasing
- Hall sensor or forcecommutation
- Step by step phasing progress prompt

Gain switch



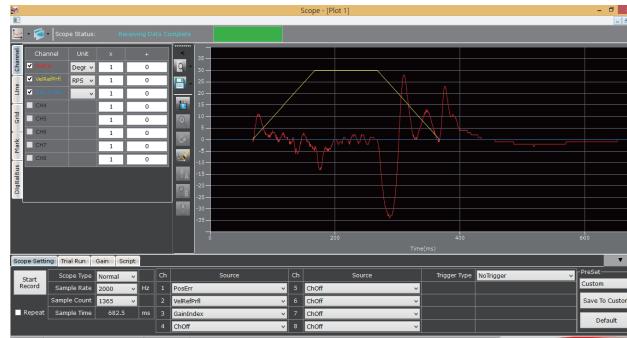
- 3 groups of position and velocity gains can be switched
- Gain-switch rule: Demand, Feedback, Error, Target, and Digital input
- Easy to fine tune for different application

Auto tune(velocity)



- Fast control loop up to 10k Hz
- Can test 3 groups of gain set
- Easy to fine tune
- Feedforward signal path
- Response Bode plot
- Bandwidth label
- Input response test with step/sine/triangle
- 3 filters on force output

Gain switch Test

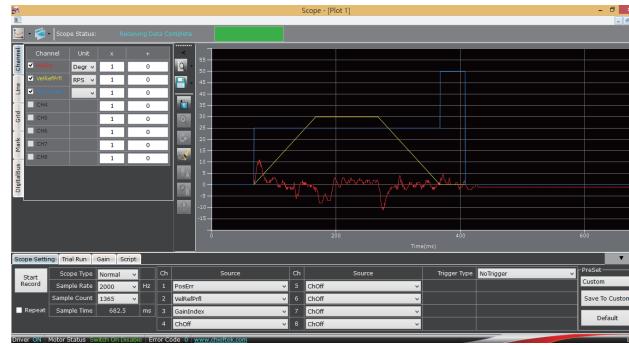


- Distance: 0.6m
- Acceleration: 3g
- Velocity: 3m/s
- Deceleration: 3g

Performance without Gain-switch
 Yellow: velocity profile
 Red: Position Error [+/- 35 count]

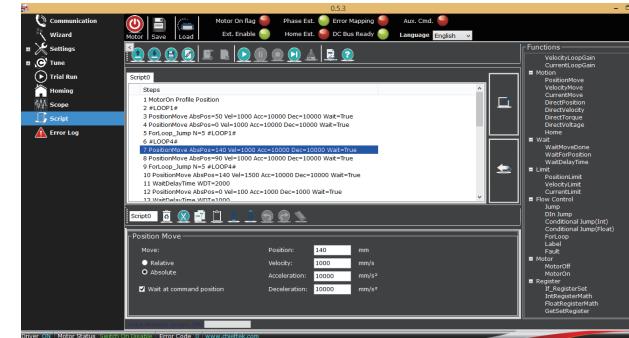
Gain switch Test

- Distance:0.6m
- Velocity:3m/s
- Acceleration:3g
- Deceleration:3g



Performance with Gain-switch
Yellow: velocity profile
Red: Position Error [± 11 count]

Scripting



Script could program motor motion with user-friendly interface.

Scope

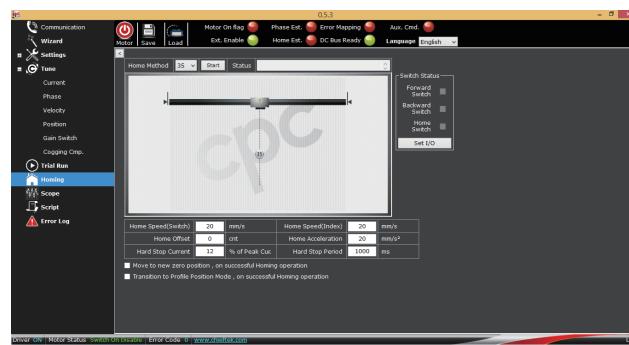


- Scope provides a real time monitor of driver information.
- User could inspect motion detail without an oscilloscope.

Ordering Information

Will	B	9	P	/230 -	H	R	E
							<input type="checkbox"/> CANopen ^(Note1) <input checked="" type="checkbox"/> EtherCAT
AC supply: 230VAC							
<input type="checkbox"/> Normal							
<input checked="" type="checkbox"/> Extended peak current ^(Note2)							
Continuous current (Amps):							
8, 20 (A-type only)							
3, 9 (B-type only)							
<input type="checkbox"/> A-type <input checked="" type="checkbox"/> B-type							
Servo Driver							

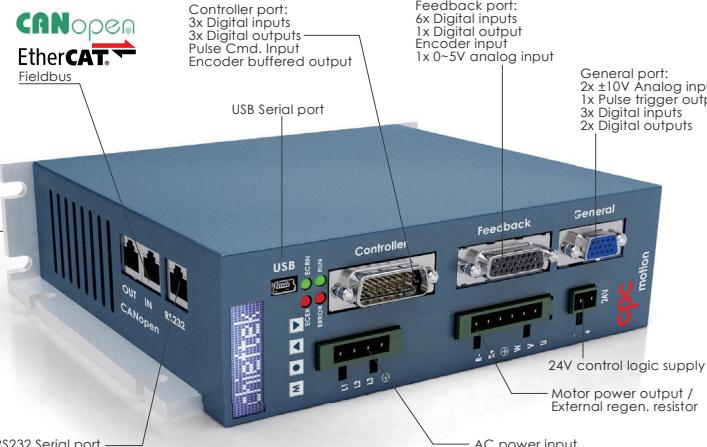
Homing



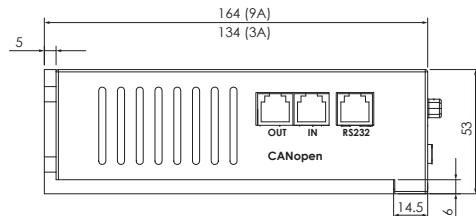
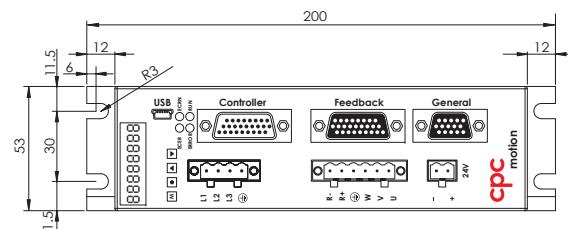
- Setup interface provides 35 kinds of homing methods.
- Also, the vivid animations explain how a homing method is performed.

Product Overview

Will1-B



Dimension



Specification

Model	Will1-B3/230	Will1-B3/230-E	Will1-B9/230	Will1-B9/230-E	Will1-B9P/230	Will1-B9P/230-E
Input Power	Voltage and Phase	1Φ 230 VAC			3Φ 230 VAC	
	DC Bus Peak Voltage (VDC)		390			
	Frequency (Hz)		50 to 60			
	Power Rating (W)	1125			3375	
Control Logi Power	Voltage Range (VDC)		24 VDC			
	Current (A)		> 0.5			
Peak power output (kW)	1.3	4.4	6.6			
Peak current output (A)	6	20	30 ^(Note2)			
Cont. current output (A)	3	9 ^(Note3)	9 ^(Note3)			
Regenerative resistor	Resistance (Ohm)	60 (option)				
	Continuous dissipation (Watt)	100 (option)				
	Pulse Braking Energy	5000 (option)				
Regenerative resistor switch cont. current (A)	10	20				
Fieldbus (DS402 V3.0)	CANopen	EtherCAT	CANopen	EtherCAT	CANopen	EtherCAT
DS402 Operation modes			PP, PV, PT, HM, CST, CSV, CSP			
Serial bus				RS232		
Motor type				Linear/Rotary PMSM		
Encoder Input	Digital	Type	A/B Incremental (RS422 signaling)			
		Work Frequency	Max. 20 Mega counts/s			
		Count Rate	$\pm 2^3$ counts			
	Analog (sin / cos)	Amplitude	IV _{p-p}			
		Work Frequency	100 kHz, 4096 Cnt/Period Interpolation			
	Absolute	Type	BiSS-C, Tamagawa, EnDat 2.2, SSI			
Feedback position error mapping			Yes			
Current control	Loop Frequency		20 KHz			
	PWM modulation		SVPWM			
	Command input		Serial, Fieldbus, ± 10 V Analog, internal software			
Velocity control	Loop Frequency		10 KHz			
	Command input		Serial, Fieldbus, ± 10 V Analog, internal software			
	Output filter		x3 (Low-pass or Notch)			
Position control	Counter range		-2, 147, 483, 648 to 2, 147, 483, 647 counts/second			
	Loop Frequency		5 KHz			
	Command input		Pulse command (A/B, Step/Dir, CW/CCW), Serial, Fieldbus, ± 10 V Analog, internal software			
Analog Input	Trajectory generator		Trapezoidal with S-curve filter			
	Counter range		-2, 147, 483, 648 to 2, 147, 483, 647 counts			
	Input type		x1 (± 10 V differential), x1 (± 10 V Single-end)			
Pulse command frequency	ADC resolution		12 bit			
	RS422		Max. 10 MHz			
	5V single-end		Max. 1 MHz			
	24V single-end		Max. 50 KHz			
Total Digital Inputs			x12 (5-24 V)			
Total Digital Outputs (open-collector)			x3 (24V, 400 mA), x3 (24 V, 200 mA)			
High speed Position compare output			x1 (RS422)			
Autotuner			Current/Velocity/Position loop gain, motor phasing setup, sin/cos encoder calibration			
Gain switch function			Yes			
Control panel			x1 (8 digit character LCD) x4 push buttons			
Software protection			Dynamic brake, motor over-current, over/under-position, over-velocity, Virtual/physical position limit switch, missing hall signal, external fault trigger			
Hardware protection			Drive over-temperature (analog), 5V output short circuit, motor over-temperature (analog)			
Dimensions (LxHxW)(mm)	200 x 134 x 53		200 x 164 x 53 (excluding optional heatsink)			
Weight (Kg)	1.2		1.6 (excluding optional heatsink)			
Operating temperature			10~40 °C			

Note 1: Only applicable for the Will1-B series.

Note 2: Only applicable for the Will1-B series. Current sensor with a wider input range is used at the cost of additional signal noise and reduced resolution. This arrangement is suitable for applications where the motor mostly operates in short, high current bursts.

Note 3: Additional heatsink required to ensure continuous operation at rated output.

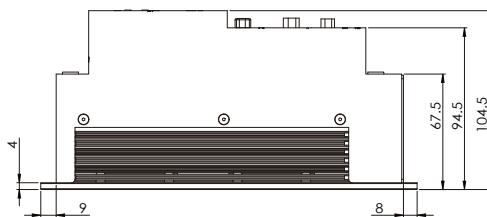
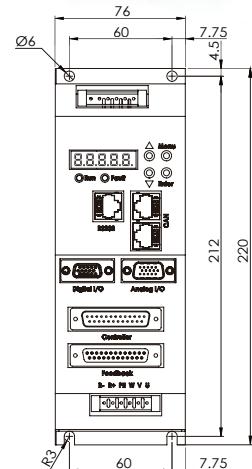
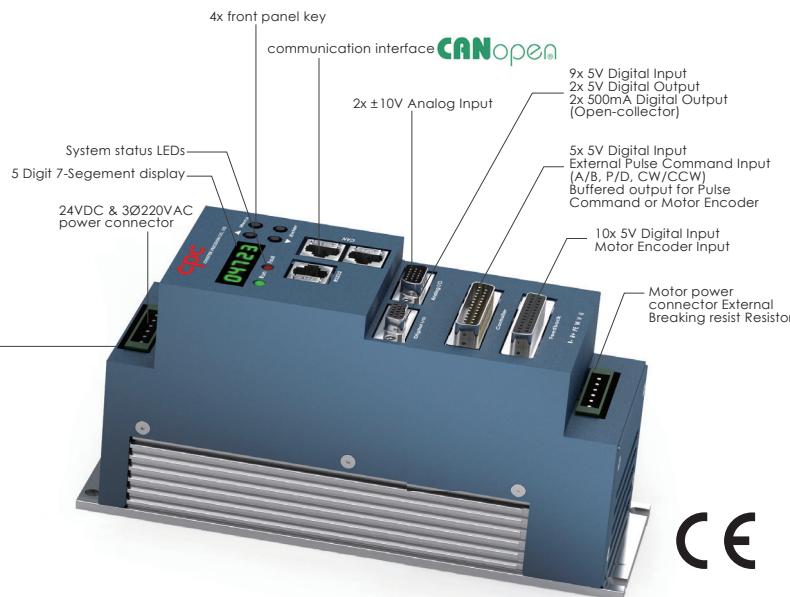
Product Overview

Will1

- Auto Phasing
- Auto Tuning
- Auto Gain Switch

- Current Filter
- Oscilloscope
- S-curve Profile

- Anti-Cogging
- Scripting



Specification

Model		Will1-8/230	Will1-20/230
Input Power	Voltage and Phase	3Ø 230 VAC	
	DC Bus Peak Voltage (V)	390	
	Frequency (Hz)	50 to 60	
	Power Rating (W)	3000	7500
Control Logi Power	Voltage Range (VDC)	24	
	Current (A)	> 0.5	
Peak power output (kW)	4.4	12	
Peak current output (A)	20	60	
Cont. current output (A)	8	20	
Regenerative resistor	Resistance (Ohm)	60	25
	Continuous dissipation (Watt)	100	200
	Pulse energy capacity (Joule)	2500	10000
Regenerative resistor switch cont. current (A)		20	
Fieldbus (DS402 V3.0)		CANopen	
DS402 Operation modes		PP, PV, PT, HM, CST, CSV, CSP	
Serial bus		RS232	
Motor type		Linear/Rotary PMSM	
Encoder Input	A/B/Z (RS422)	20 MCnt/s	
	Sin/Cos (1V _{pp})	-	
	SSI (RS422)	-	
	BISS	-	
Feedback position error mapping		Yes	
Current control	Loop Frequency	20 KHz	
	PWM modulation	SVPWM	
	Command input	Serial, Fieldbus, ±10 V Analog, internal software	
Velocity control	Loop Frequency	10 KHz	
	Command input	Serial, Fieldbus, ±10 V Analog, internal software	
	Output filter	x3 (Low-pass or Notch)	
	Counter range	-2, 147, 483, 648 to 2, 147, 483, 647 counts/second	
Position control	Loop Frequency	5 KHz	
	Command input	Pulse command (A/B, Step/Dir, CW/CCW), Serial, Fieldbus, ±10 V Analog, internal software	
	Trajectory generator	Trapezoidal with S-curve filter	
	Counter range	-2, 147, 483, 648 to 2, 147, 483, 647 counts	
Analog Input	Input type	±10 V differential	
	ADC resolution	12 bit	
Pulse command frequency	RS422	Max. 10 MHz	
	5V single-end	Max. 1 MHz	
	24V single-end	-	
Total Digital Inputs		x22 (3.3-5 V)	
Total Digital Outputs (open-collector)		x2 (24 V, 500 mA), x6 (24 V, 20 mA)	
High speed Position compare output		-	
Total Analog Inputs		x2 (±10 V differential)	
Autotuner		Current/Velocity/Position loop gain, motor phasing setup, sin/cos encoder calibration	
Gain switch function		Yes	
Control panel		x1 (5 digit 7-segment LED) x4 push buttons	
Software protection		Dynamic break, motor over-current, over/under-position, over-velocity, Virtual/physical position limit switch, missing hall signal, external fault trigger	
Hardware protection		Drive over-temperature (on/off), motor over-temperature (on/off)	
Dimensions (LxHxW)(mm)	220 x 105 x 76	270 x 195 x 94	
Weight (Kg)	1.6	3.7	
Operating temperature		10~40 °C	